

Preliminary experiments for Streaming SVD

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Outline

- 1 Cold-start rSVD
- 2 Warm-Started Streaming SVD
- 3 Simulated Data Generation
- 4 Synthetic Results
- 5 Control Experiment: Independent Matrices
- 6 Parameter Sweep Results
- 7 Real Data Experiment

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Cold-Start rSVD Algorithm

Algorithm Randomized SVD (Halko et al.)

Require: $A \in \mathbb{R}^{m \times n}$, rank k , oversampling p , iterations q

Ensure: $U \in \mathbb{R}^{m \times k}$, $\mathbf{s} \in \mathbb{R}^k$, $V^T \in \mathbb{R}^{k \times n}$

- 1: Draw $\Omega \in \mathbb{R}^{n \times (k+p)} \sim \mathcal{N}(0, 1)$
 - 2: $Y \leftarrow A\Omega$
 - 3: **for** $i = 1$ to q **do**
 - 4: $Y \leftarrow A(A^T Y)$
 - 5: **end for**
 - 6: $Q, _ \leftarrow \text{QR}(Y)$
 - 7: $B \leftarrow Q^T A$
 - 8: $U_{\text{hat}}, \mathbf{s}, V^T \leftarrow \text{SVD}(B)$
 - 9: $U \leftarrow QU_{\text{hat}}$
 - 10: **return** $U_{:,1:k}, \mathbf{s}_{1:k}, V^T_{1:k,:}$
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Warm-Started rSVD Algorithm

Algorithm Warm-Start Randomized SVD

Require: $A \in \mathbb{R}^{m \times n}$, previous basis U_{prev} , rank k , oversampling p , iterations q

Ensure: $U \in \mathbb{R}^{m \times k}$, $\mathbf{s} \in \mathbb{R}^k$, $V^T \in \mathbb{R}^{k \times n}$

- 1: $G \leftarrow A^T U_{\text{prev}}$ ▷ Warm-start projection
 - 2: $Y_1 \leftarrow AG$ ▷ Prior subspace component
 - 3: Draw $\Omega \in \mathbb{R}^{n \times p} \sim \mathcal{N}(0, 1)$
 - 4: $Y_2 \leftarrow A\Omega$ ▷ Exploration component
 - 5: $Y \leftarrow [Y_1 \mid Y_2]$ ▷ Concatenate
 - 6: **for** $i = 1$ to q **do**
 - 7: $Y \leftarrow A(A^T Y)$
 - 8: **end for**
 - 9: $Q, _ \leftarrow \text{QR}(Y)$
 - 10: $B \leftarrow Q^T A$
 - 11: $U_{\text{hat}}, \mathbf{s}, V^T \leftarrow \text{SVD}(B)$
 - 12: $U \leftarrow QU_{\text{hat}}$
 - 13: **return** $U_{:,1:k}, \mathbf{s}_{1:k}, V_{1:k,:}^T$
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Initial Matrix Generation

- Generate low-rank matrix: $S = U\text{diag}(\mathbf{s})V^T$
 - $U \in \mathbb{R}^{m \times r}$: random orthonormal basis (QR)
 - $V \in \mathbb{R}^{n \times r}$: random orthonormal basis (QR)
 - Singular values with exponential decay: $s_i = \exp(-\text{decay} \cdot i)$
- Parameters:
 - Dimensions: m, n (rows, columns)
 - True rank: r
 - Decay rate: decay (controls spectral concentration)

Matrix Perturbation Process

- At each time step: $S^{(t+1)} = S^{(t)} + E^{(t)}$
- Perturbation magnitude controlled by: $\|E\|_F = \eta \cdot \|S^{(t)}\|_F$
- Noise structure options:
 - Full-rank noise: $E \in \mathbb{R}^{m \times n}$ (general perturbation)
 - Low-rank noise: $E = U_E V_E^T$ (structured perturbation)
- Allows systematic evaluation of algorithm robustness under different perturbation regimes

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Experiment Parameters

Parameter	Value
Matrix size ($m \times n$)	1000 \times 1000
Target rank (k)	20
Time steps (T)	10
Perturbation magnitude (η)	0.05
Cold-start oversampling (p_{cold})	10
Warm-start oversampling (p_{warm})	5
Power iterations (q)	0
Random seed	42

- **Relative Frobenius error**

$$\frac{\|A - U\text{diag}(\mathbf{s})V^T\|_F}{\|A\|_F}$$

- **Relative spectral error estimate**

$$\frac{\|(I - UU^T)A\|_2}{\|A\|_2}$$

estimated in code by power iteration (`rel_spec_error_est`).

Metrics

- **Subspace distance** (principal-angle based)

$$\sin \theta(U_1, U_2) = \sqrt{1 - \sigma_{\min}(U_1^T U_2)^2}$$

and a Frobenius-angle variant for aggregate mismatch.

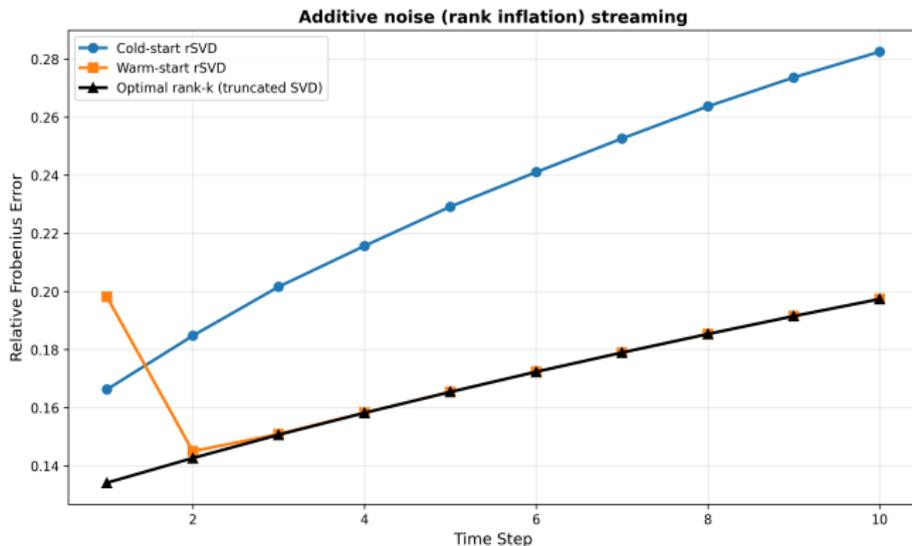
- **Optimal rank- k baseline**

$$\frac{\|A - A_k\|_F}{\|A\|_F} = \sqrt{\frac{\sum_{i>k} \sigma_i^2}{\sum_i \sigma_i^2}}$$

computed via singular values (when `compute_optimal=True`).

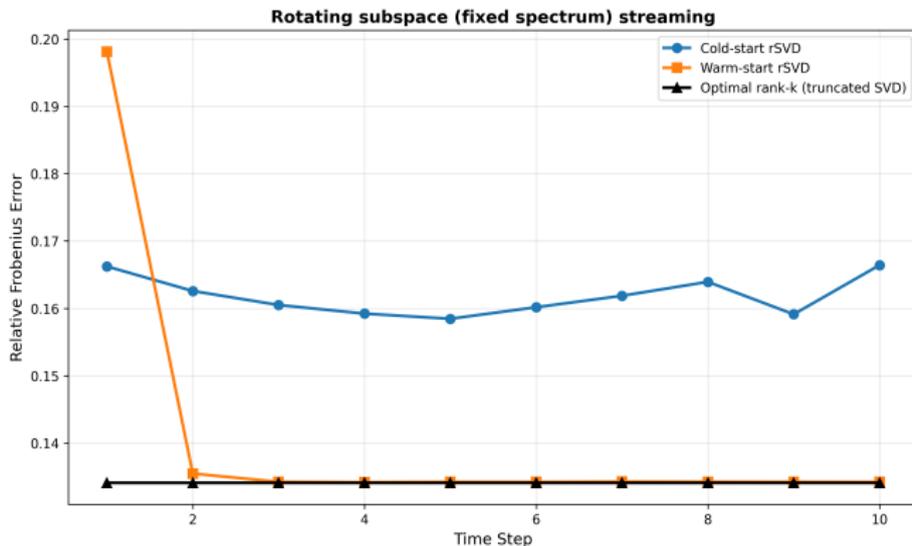
Experiment 1: Additive Perturbations

- $S_t = S_{t-1} + E_t$, with $\|E_t\|_F = \eta \|S_{t-1}\|_F$.
- Consequence: energy beyond rank k accumulates, so even the **optimal rank- k** error increases over time.
- Cold- and warm-start are compared against the best possible truncated-SVD baseline.

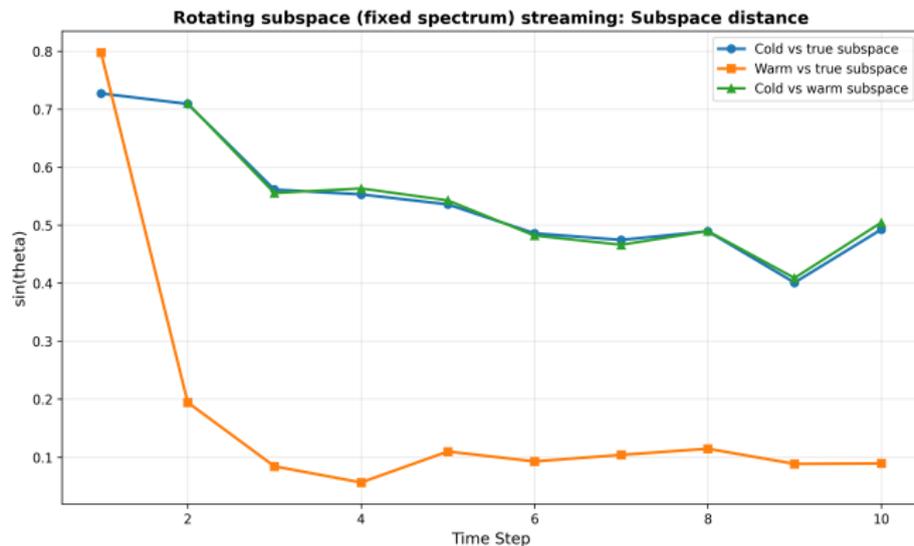


Experiment 2: Rotating Subspace

- $S_t = U_t \text{diag}(\mathbf{s}) V_t^T$ with fixed \mathbf{s} ; U_t and V_t rotate slowly via small orthogonal updates.
- Consequence: **optimal rank- k** error remains approximately constant; method performance reflects tracking ability rather than rank inflation.



Rotating Regime: Subspace Tracking



Key Findings

- **Warm-start improves approximation quality** across the stream
 - Relative Frobenius error remains consistently below cold-start
 - Relative spectral error is also lower over timesteps
- **Lower approximation error:** Warm-start achieves 24.6% better error on average
 - Leverages prior subspace information
 - Better exploration of perturbation direction
- **Consistent behavior:** Error ratio remains stable across 10 time steps (0.754)
 - Demonstrates robustness to streaming perturbations
 - Prior basis remains informative over time

Summary Results

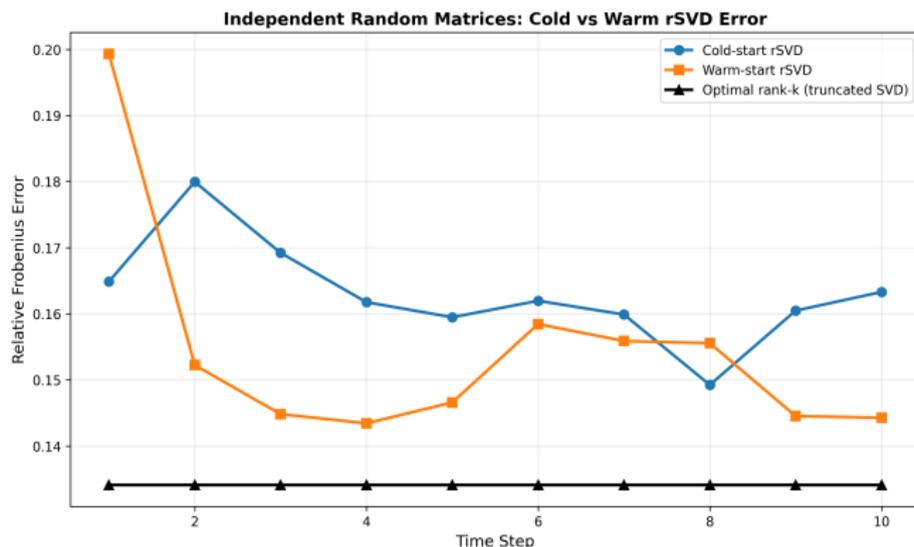
Reported quantities: all error values are averages over timesteps of relative Frobenius error; improvement is the warm-vs-cold relative reduction with warm/cold ratio in parentheses.

Regime	Cold	Warm	Optimal
Additive noise streaming	0.2310	0.1743	0.1676
Rotating subspace streaming	0.1619	0.1408	0.1341
Additive warm improvement	24.6% (ratio 0.771)		
Rotating warm improvement	13.0% (ratio 0.869)		

Outline

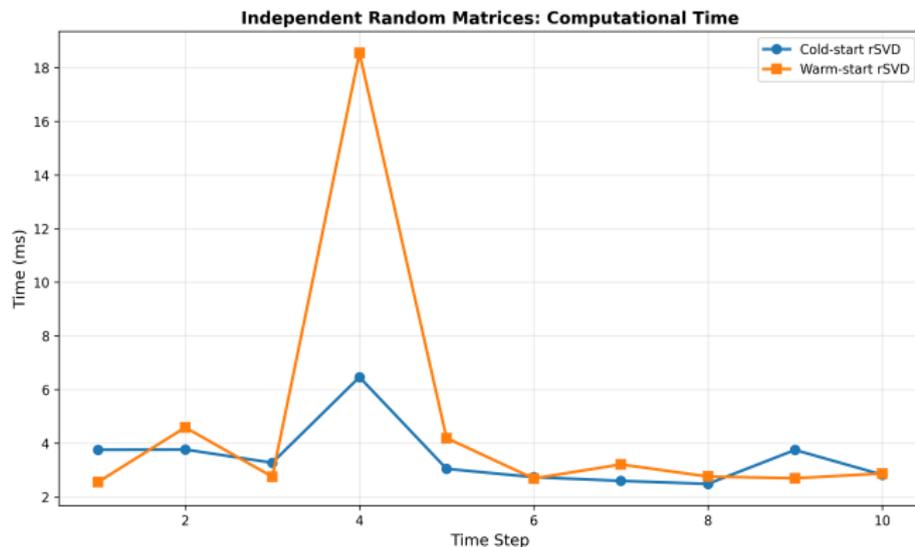
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Independent Random Matrices: Error Comparison



- Matrices at each timestep are generated independently.
- This removes temporal correlation between snapshots.
- Warm-start rSVD should therefore provide little or no advantage.

Independent Random Matrices: Runtime



- Cold and warm algorithms perform similar work.
- Any improvement seen in correlated experiments should disappear here.

Interpretation

- In the independent matrix setting there is no shared structure between timesteps.
- The previous singular subspace contains no useful information for the next snapshot.
- As expected, warm-start rSVD performs similarly to cold-start rSVD.
- This experiment serves as a control validating the warm-start hypothesis.

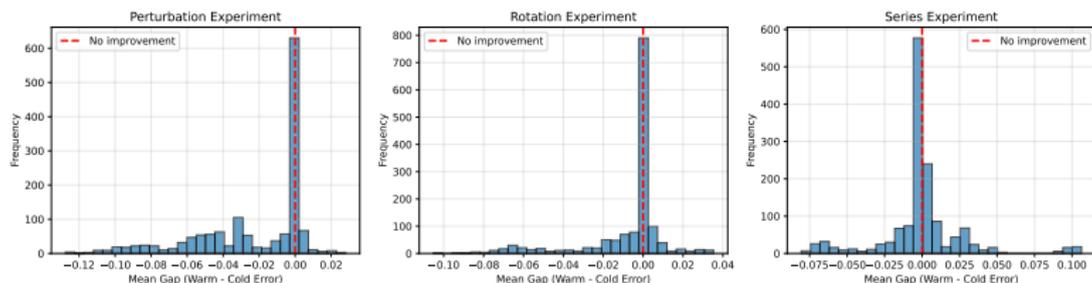
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Sweep Setup (Completed Run)

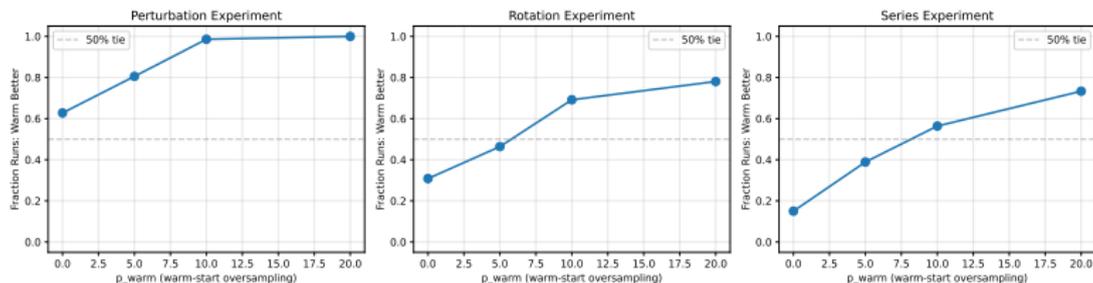
- Full grid executed across **series**, **perturbation**, and **rotation** regimes.
- Total runs: **4320** (all combinations of m , n , k , p_{cold} , p_{warm} , q , with 5 seeds).
- Metrics shown are error-only: mean gap (warm – cold), mean ratio (warm/cold), and fraction warm better.
- CSV outputs: `results/sweep_raw.csv` and `results/sweep_summary.csv`.

Sweep Results: Error-Gap Distribution



- Negative mean gap indicates warm-start has lower error than cold-start.
- Perturbation and rotation show broader mass on the negative side than the independent-series control.

Sweep Results: Warm Advantage vs p_{warm}



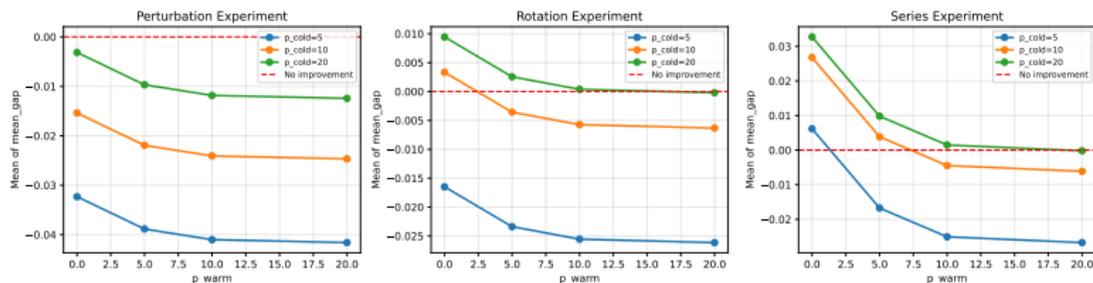
- Increasing warm exploration generally improves consistency of warm-start wins.
- Effect is strongest in perturbation and more moderate in rotation; control series is weakest overall.

Sweep Summary Across All Configurations

Regime	Avg gap	Avg ratio	Warm-win frac
Perturbation	-0.0231	0.9046	0.8549
Rotation	-0.0076	0.9370	0.5611
Series (control)	0.0001	0.9870	0.4590

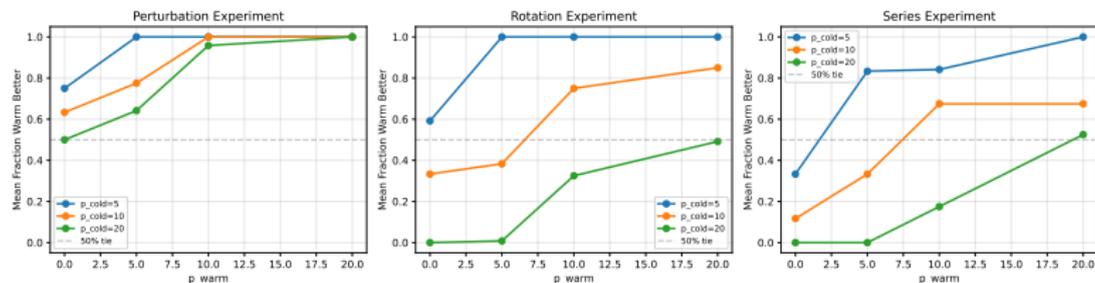
- Warm-start gives the clearest average error improvement in **perturbation**.
- **Series** is near parity, consistent with the no-temporal-correlation control.

Sampling Dimensions: Effect on Mean Gap



- Lines show mean gap versus p_{warm} , grouped by p_{Cold} .
- More negative values are better for warm-start.

Sampling Dimensions: Effect on Warm-Win Frequency



- Warm-win frequency rises with larger p_{warm} in all three regimes.
- Lower p_{cold} generally favors warm-start consistency.

Largest Parameter Effects (from Sweep CSV)

Parameter	Range of global avg mean-gap
p_{cold}	0.0272
q	0.0225
p_{warm}	0.0173
k	0.0109
m	0.0004
n	0.0003

- Biggest overall effect is from **sampling dimensions**, led by p_{cold} , then p_{warm} .
- Global trend for p_{warm} : 0 \rightarrow 20 moves avg gap from +0.0012 to -0.0160.
- Global trend for p_{cold} : 5 \rightarrow 20 moves avg gap from -0.0256 to +0.0016.

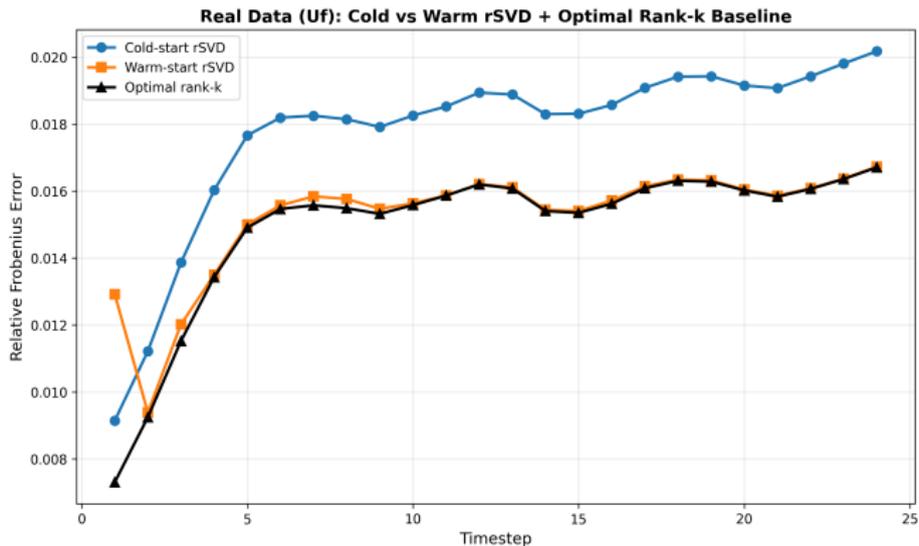
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Real Data Setup

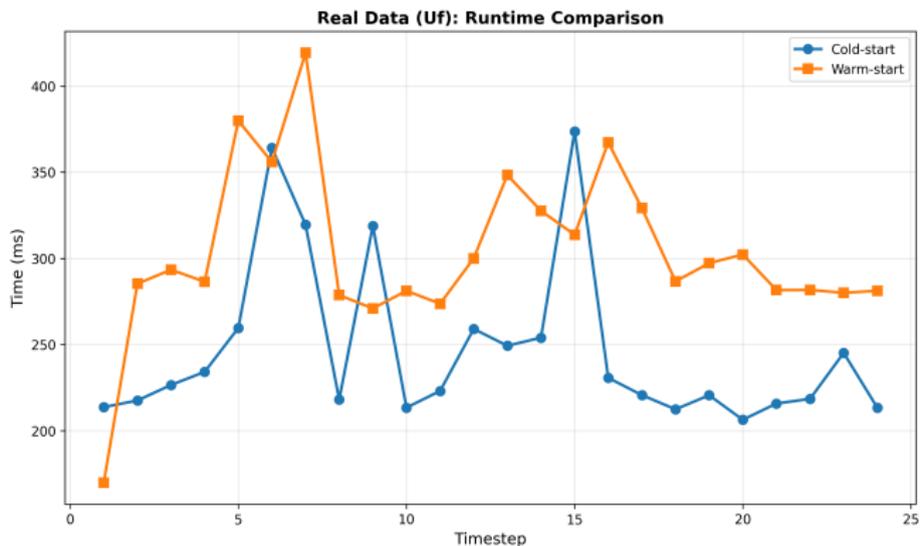
- **Data source:** 24 timesteps of 3D volumetric data (Uf01–Uf24.bin, full 24-hour cycle)
 - Each file: $100 \times 500 \times 500$ float32 (z, y, x order)
 - Missing/outlier values: pre-processed to 0
- **Matrix unfolding:** reshape volume to unstructured matrix $A_t \in \mathbb{R}^{250000 \times 100}$
 - Rows: spatial (x,y) points, $500 \times 500 = 250,000$
 - Columns: z-levels, 100 levels
- **Optimal baseline:** computed exactly from Gram matrix $G = A_t^T A_t$ (100×100 only)
 - Avoids costly full SVD of $250,000 \times 100$ matrix
 - Exact truncated-SVD Frobenius error tail

Cold vs Warm rSVD on Real Data



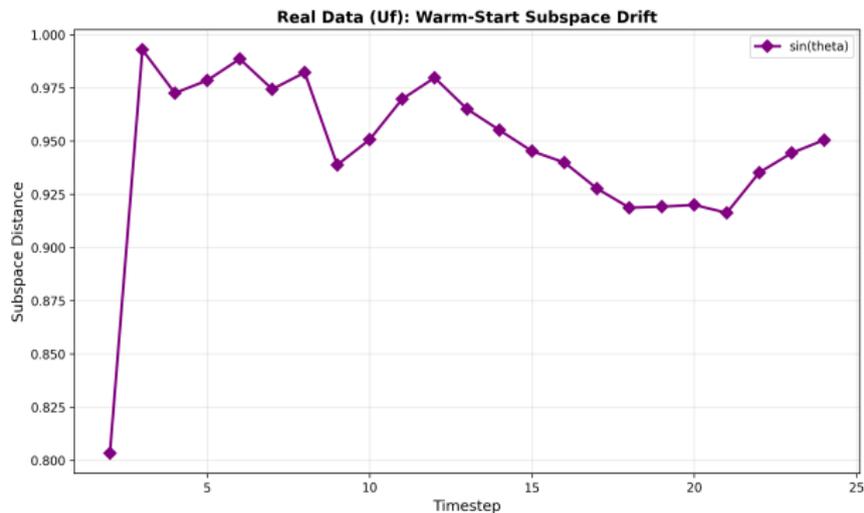
- Cold-start: learns from scratch; error gap indicates evolving rank structure
- Warm-start: reuses prior basis; adapts to subspace drift
- Optimal: fundamental limit for rank- k approximation

Weather Results: Runtime



- Cold-start: ~ 0.247 s/step
- Warm-start: ~ 0.304 s/step
- Trade-off: 23.0% slower per-step, but lower error on streaming data

Weather Results: Subspace Drift



- Subspace distance (sin of principal angles) between consecutive warm-start bases
- High drift (~ 0.95) indicates large changes in dominant subspace structure
- Warm initialization remains useful despite this drift

Weather Results Summary

Real Data (Uf01–Uf24): Average performance over 24 timesteps (full day cycle)

Method	Avg. Rel. Fro. Error	Avg. Time (s)
Cold rSVD	0.01774	0.2469
Warm rSVD	0.01524	0.3037
Optimal rank- k	0.01492	—

- **Warm-start improvement:** 14.1% error reduction (ratio 0.859 vs cold)
- **Gap to optimal:** Warm 2.2% above optimal, Cold 18.9% above optimal
- **Runtime trade-off:** Warm-start increases per-step time by 23.0%
- **Key insight:** Over full diurnal cycle, warm-start benefits accumulate; maintains robustness despite persistent subspace drift (≈ 0.95) from evolving meteorological patterns